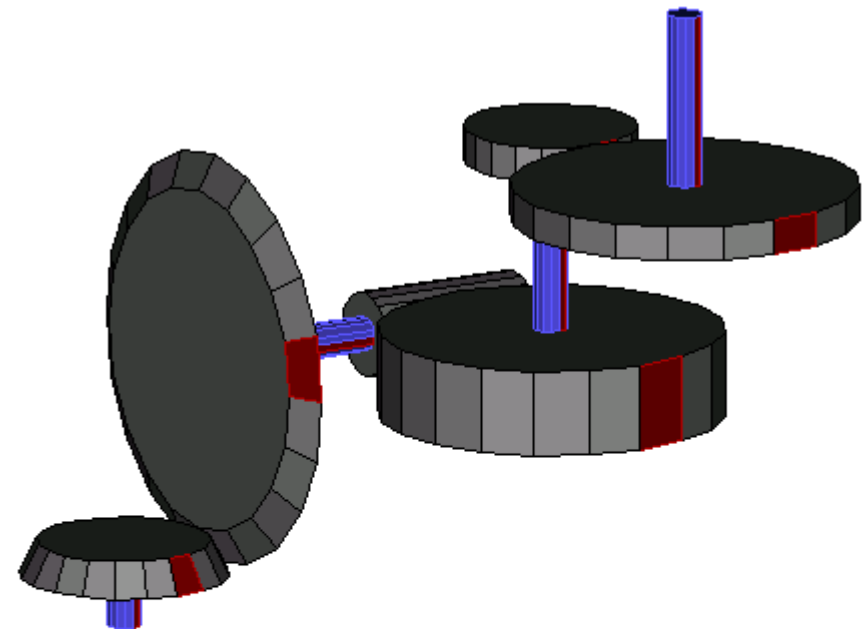


Qualitative Design of Compact Transmission Mechanisms with Standard Components

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Introduction

- *General context*

3D machine design
from written specifications

- *Purpose of this work*

A **software wizzard**
for **preliminary design**
of transmission mechanisms

- *Type of mechanisms*

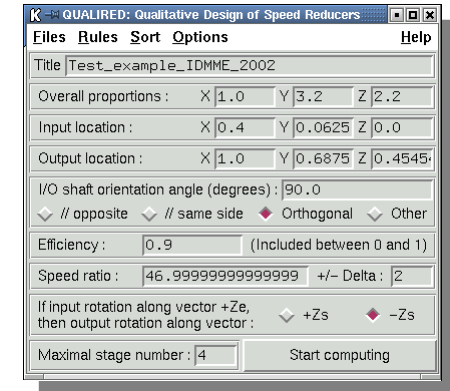
- High ratio transmissions
- Multi- stage mechanism
 - Which stage ?
 - In what order ?
 - Where in space ?

- *Summary*

1 - Basic concepts

2 - Synthesis method

3 - Concluding example



QUALIRED: Qualitative Design of Speed Reducers

Files Rules Sort Options Help

Title: Test_example_IDMME_2002

Overall proportions : X | 1.0 Y | 3.2 Z | 2.2

Input location : X | 0.4 Y | 0.0625 Z | 0.0

Output location : X | 1.0 Y | 0.6875 Z | 0.4545

I/O shaft orientation angle (degrees) : 90.0
// opposite // same side Orthogonal Other

Efficiency : 0.9 (Included between 0 and 1)

Speed ratio : 46.99999999999999 +/- Delta : 2

If input rotation along vector +Ze, then output rotation along vector : +Zs -Zs

Maximal stage number : 4 Start computing



Context

- References :

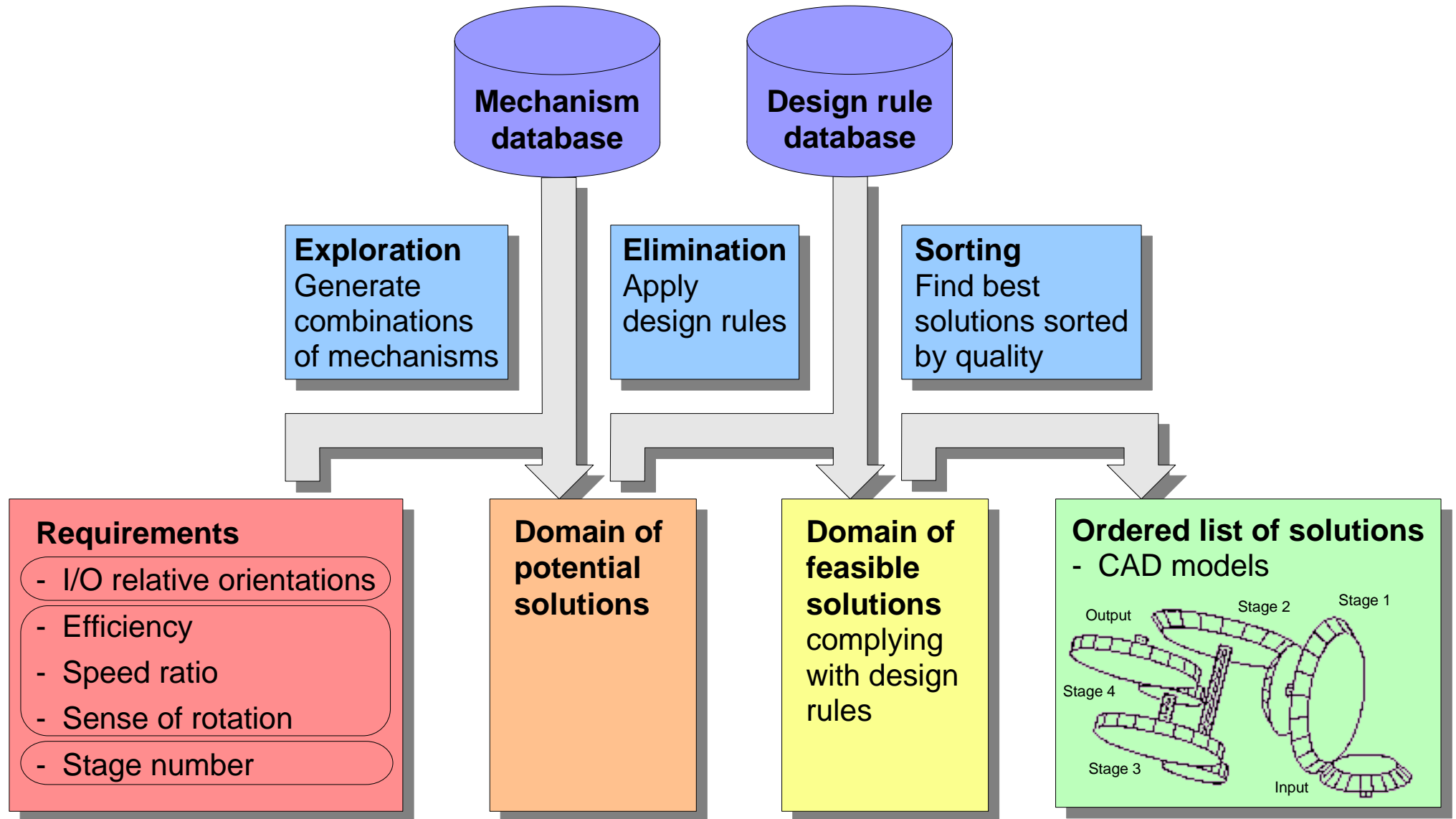
- [Chakrabarti and Bligh 96]
Synthesis of transmission mechanisms with multiple I/O
Combination of mechanical modules
Orthogonality restrictions
- [Kota and Chiou 92]
Synthesis method for compound mechanisms
Qualitative matrix representation
- [Joskowicz and Sacks 93]
Kinematic **analysis** of gear boxes and transmissions
- [Forbus, Nielsen and Faltings 91]
Qualitative kinematics and dynamics for **analysis** of complex mechanisms

- Previous works :

- [Fauroux and Sartor 97]
Qualitative synthesis method for exploring domain of feasible solutions
- [Fauroux, Sanchez, Sartor and Martins 98]
Fuzzy logic evaluation of solution

- The idea :
 - Improving synthesis method for transmission mechanisms
 - Including **qualitative analysis** of solutions for getting a better characterization

Method Architecture



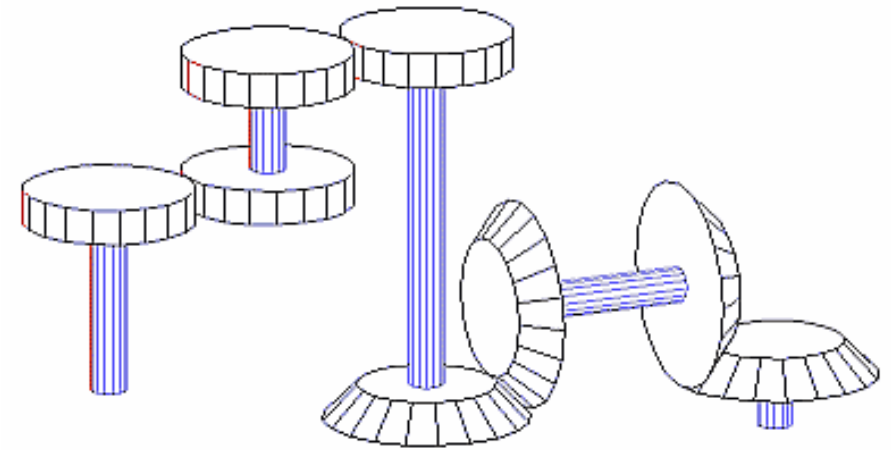
- A method improving creativity
- Exhaustive exploration of feasible solutions



- Qualitative solutions are too vague
- Many equivalent good solutions
- How to differentiate them ?

Qualitative Solutions

- Qualitative solutions are too vague
 - Qualitative shape of parts
 - Relative ordering of parts (connectivity)
 - **Not** the final dimensions
 - **Not** the final orientations



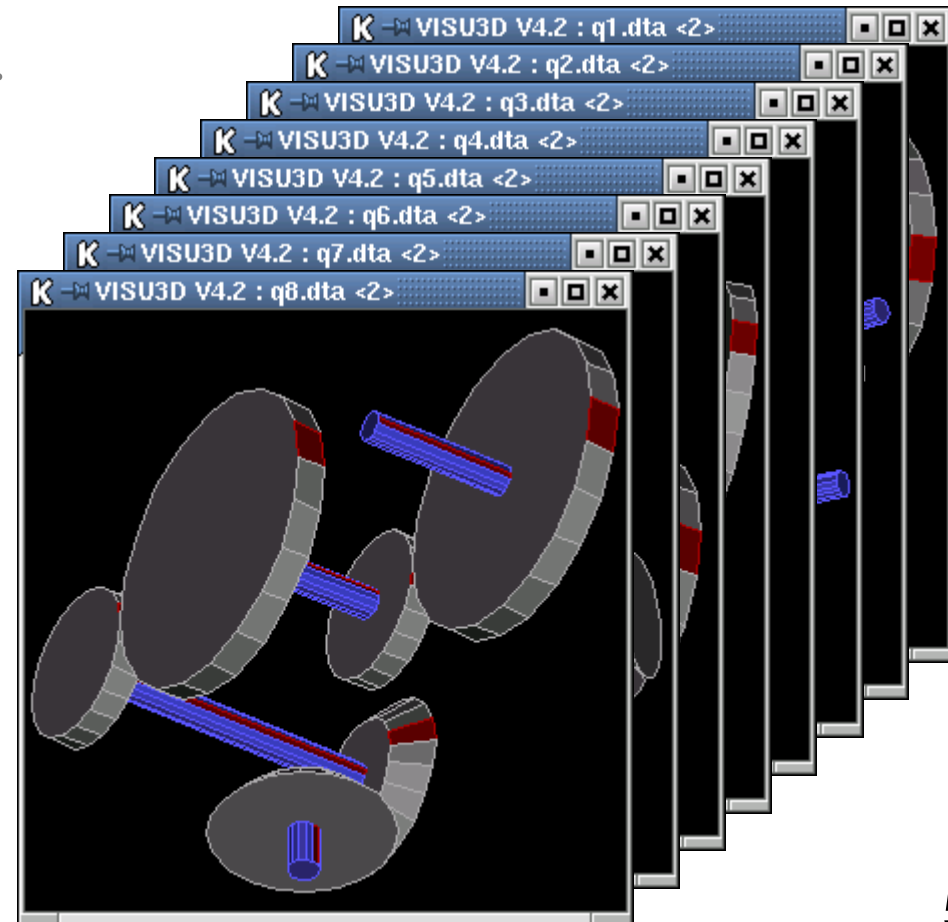
A rubber model

Demo

- Good qualitative solutions are often not easy to differentiate
 - Qualitative solutions give a good start to designers...
 - ...but need to be enriched in information

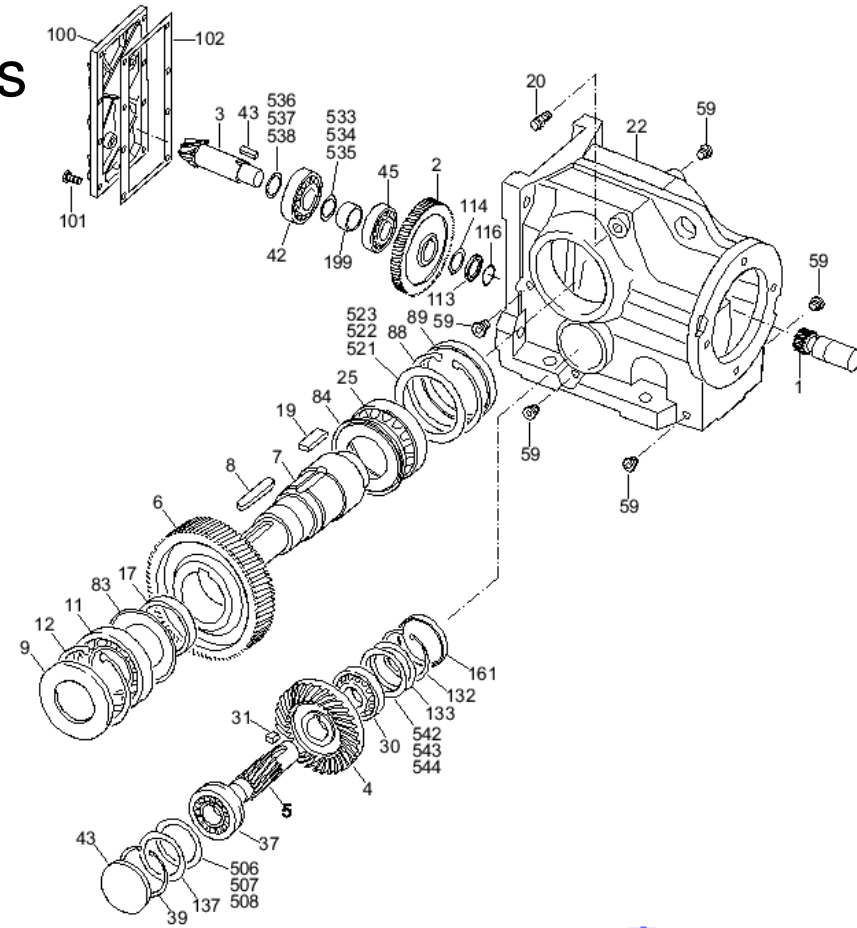
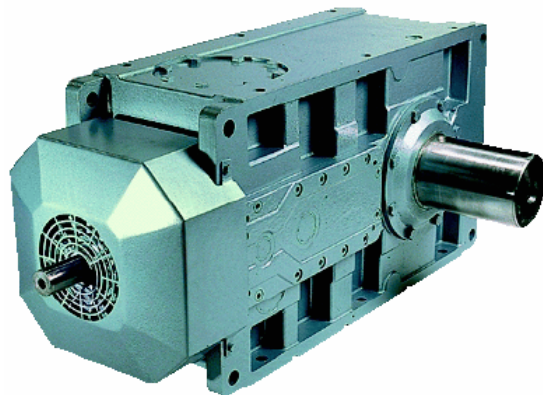
Example : 1008 solutions and 8 rated N° 1
Which to choose ?

- Idea : try to reproduce human mind

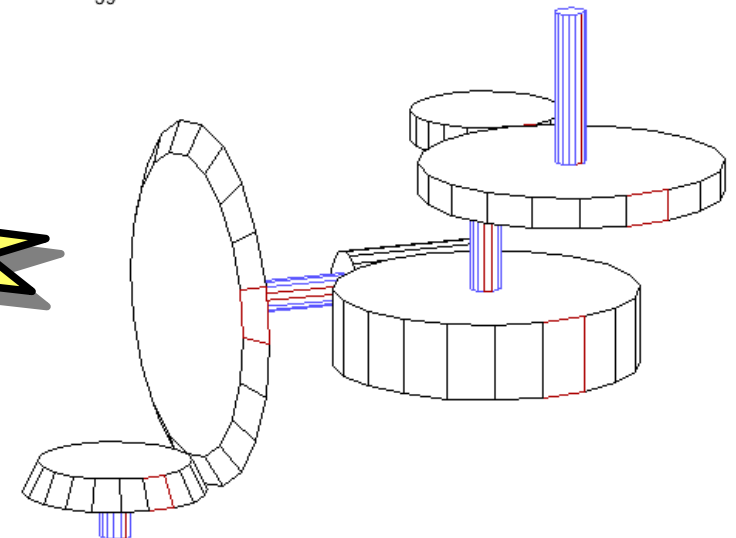


Standard Orientations

- Enriching the model by orientating stages
- 4 standard values : $0^\circ / 90^\circ / 180^\circ / 270^\circ$
 - Strong assumption but corresponding to the vast majority of industrial mechanisms
 - Permits a fast exploration of mechanism layouts
 - May be refined later

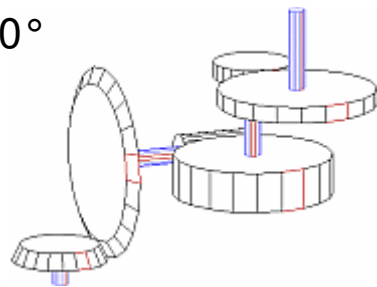


- A given mechanism can take a great number of layouts
 - 2 angles
 - 4 values per angle
 - 16 combinations

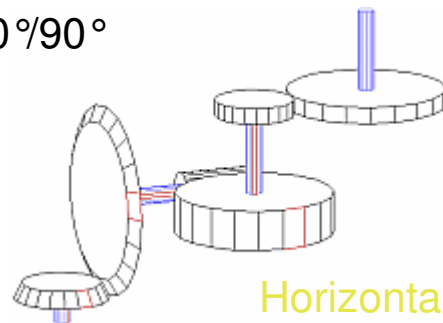


Standard Orientations

0°/0°

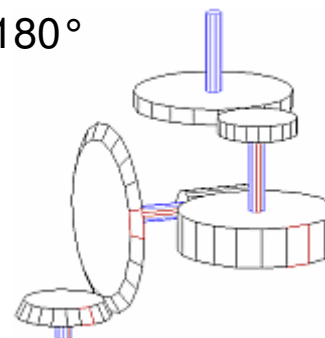


0°/90°

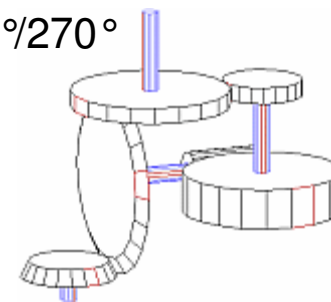


Horizontal

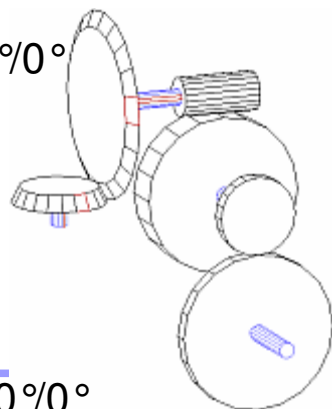
0°/180°



0°/270°

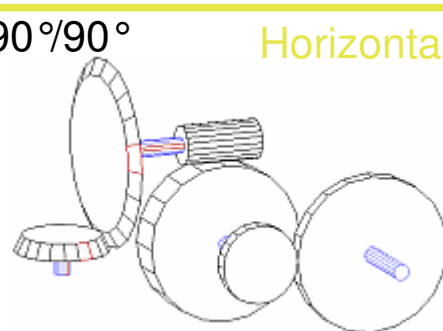


90°/0°



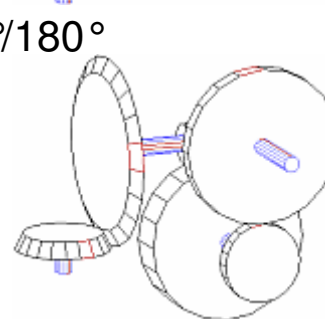
Vertical

90°/90°

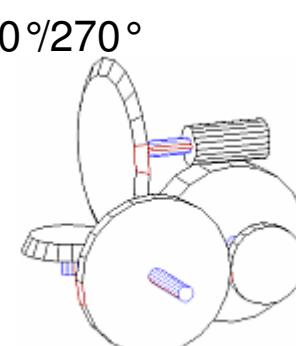


Horizontal

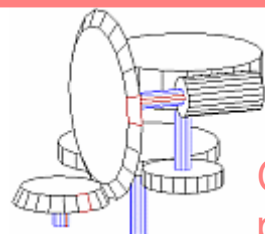
90°/180°



90°/270°

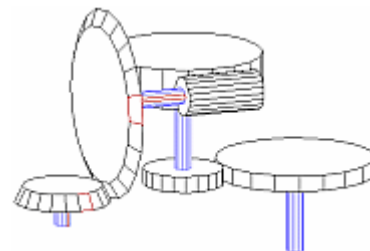


180°/0°

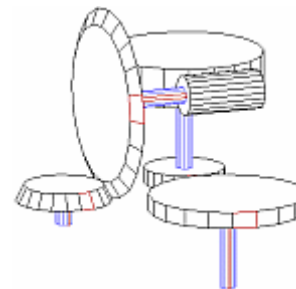


Compact

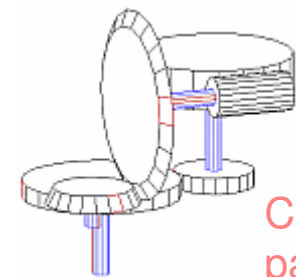
180°/90°



180°/180°

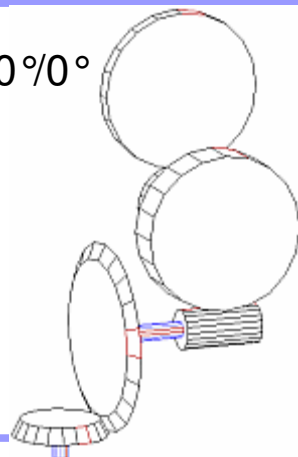


180°/270°



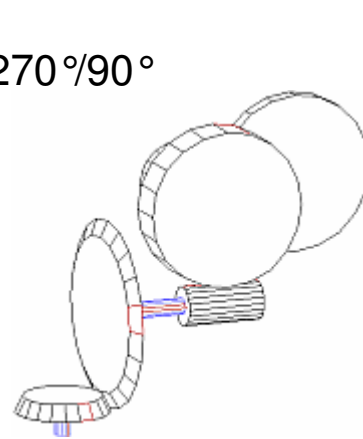
Compact

270°/0°

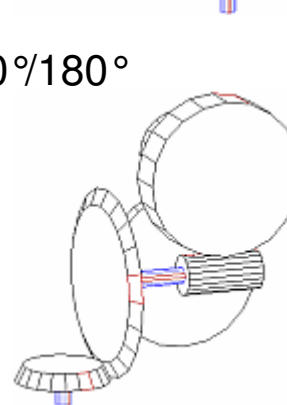


Vertical

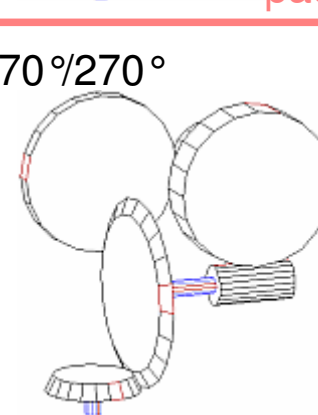
270°/90°



270°/180°



270°/270°



Mechanism Compactness

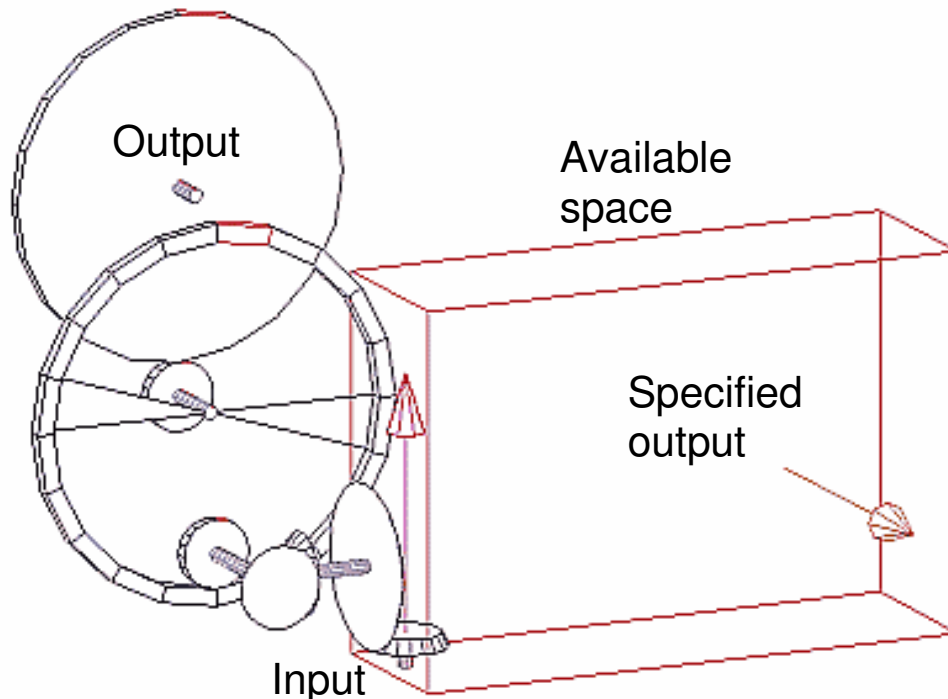
- **Compactness** : a way for differentiating solutions

- Compact = fits the available space

- No spoilt space inside
- No big parts crossing outside

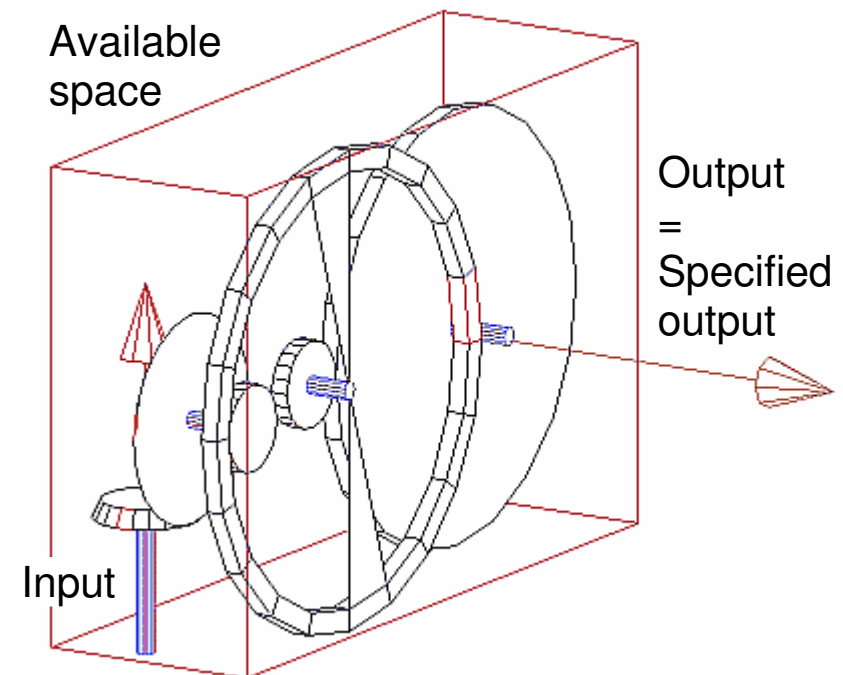
- Not Compact

- Space is horizontal
- Mechanism is vertical
- Mechanism is totally outside



- Compact

- Mechanism has good overall orientation
- Mechanism has good proportions



Standard Mechanisms (1/2)

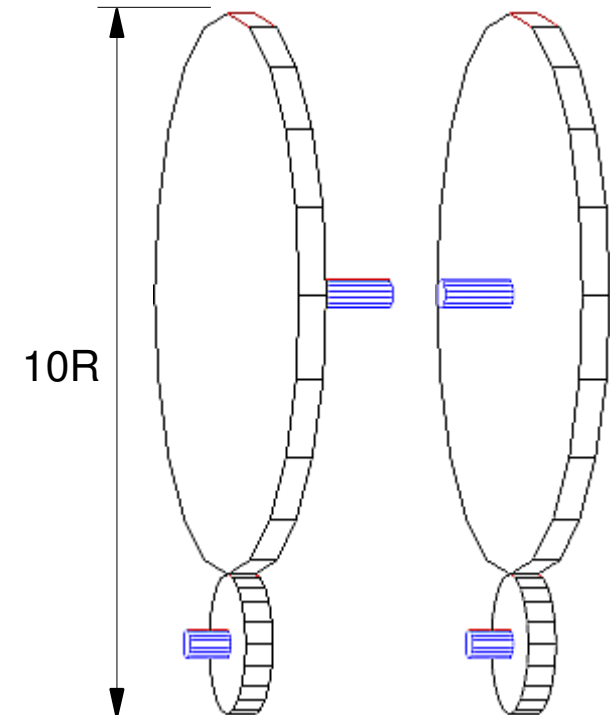
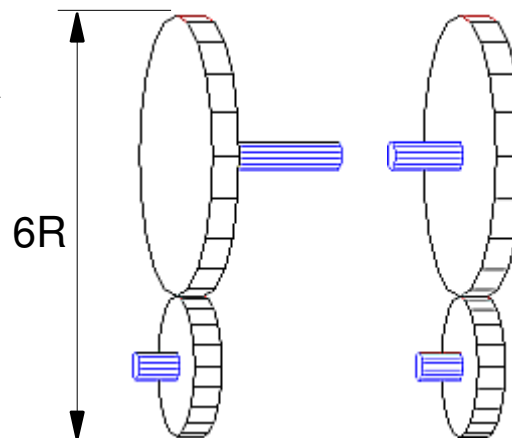
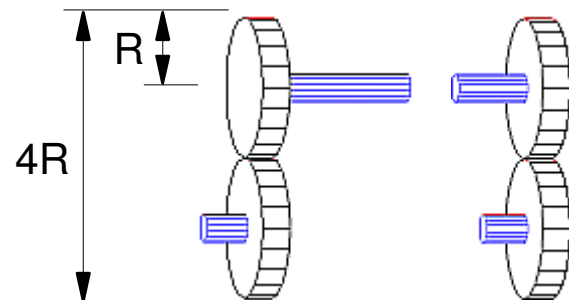
• Semi- dimensioned mechanisms

Example : cylindrical gear

- Diameters have given values - > Fixed ratio
- Pitch diameter or tooth width may be kept undefined

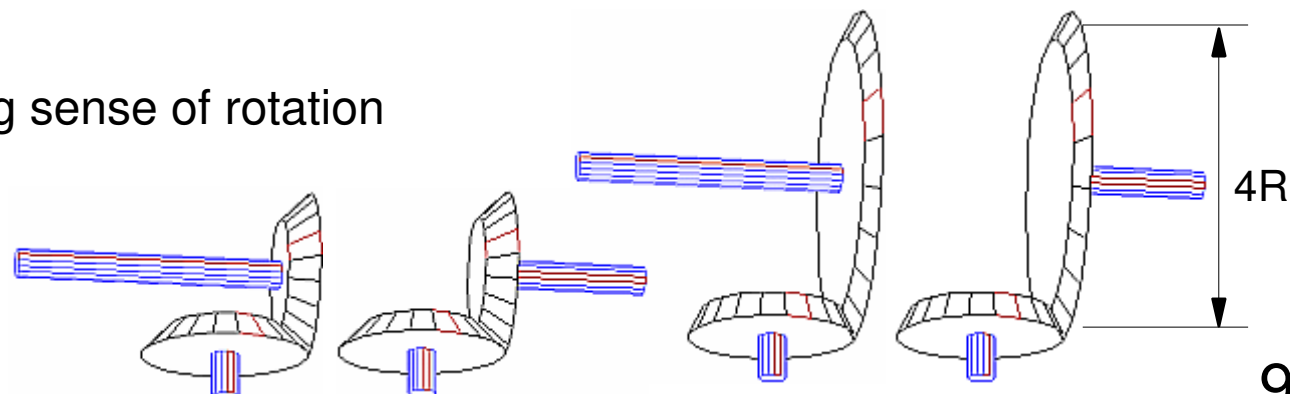
• Cylindrical gear sets

- Opposite shafts / Shafts on the same side
- Ratios 1, 2 or 4
- Dimensions : $4R$, $6R$, $10R$



• Bevel gear sets

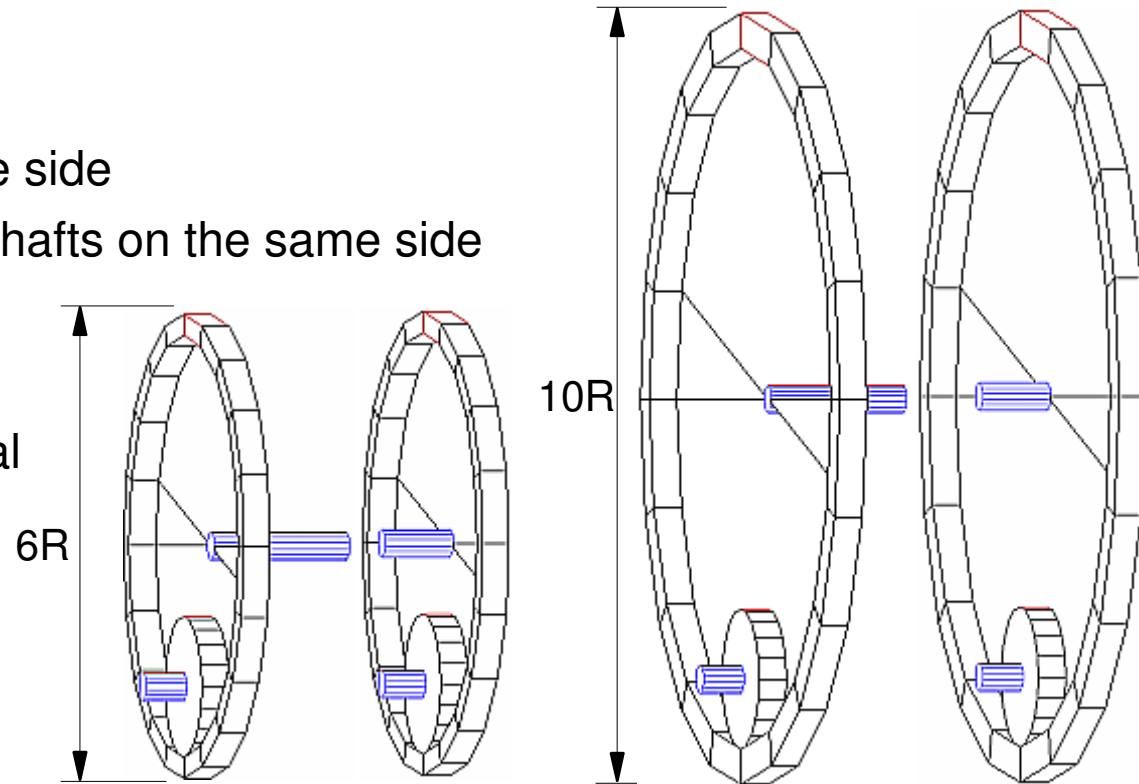
- Two shaft settings for reversing sense of rotation
- Ratios 1, or 2
- Big wheels are expensive so ratios are limited



Standard Mechanisms (2/2)

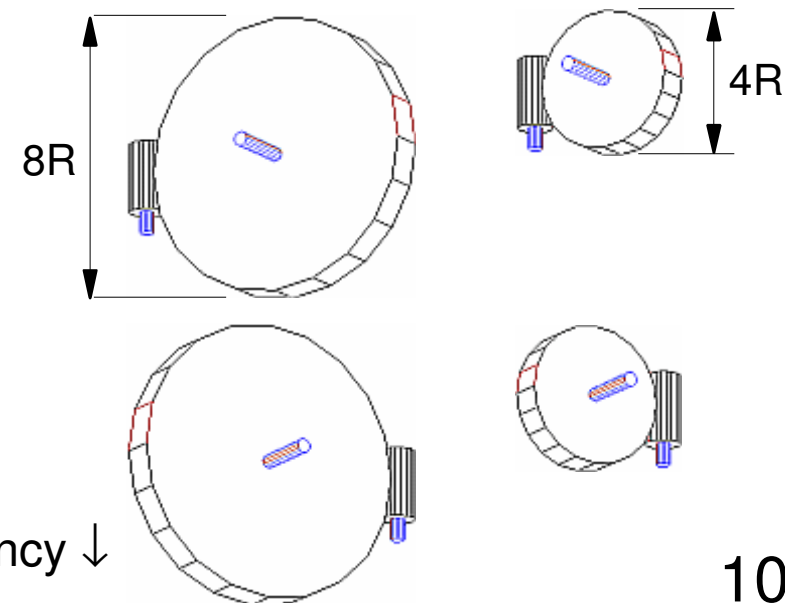
Internal cylindrical gear sets

- Opposite shafts / Shafts on the same side
- Ratio 2 gives part interference with shafts on the same side
- Ratios 3 or 5
- Dimensions : $6R$ or $10R$
- With same overall dimension, internal gear sets reduce more than external ones



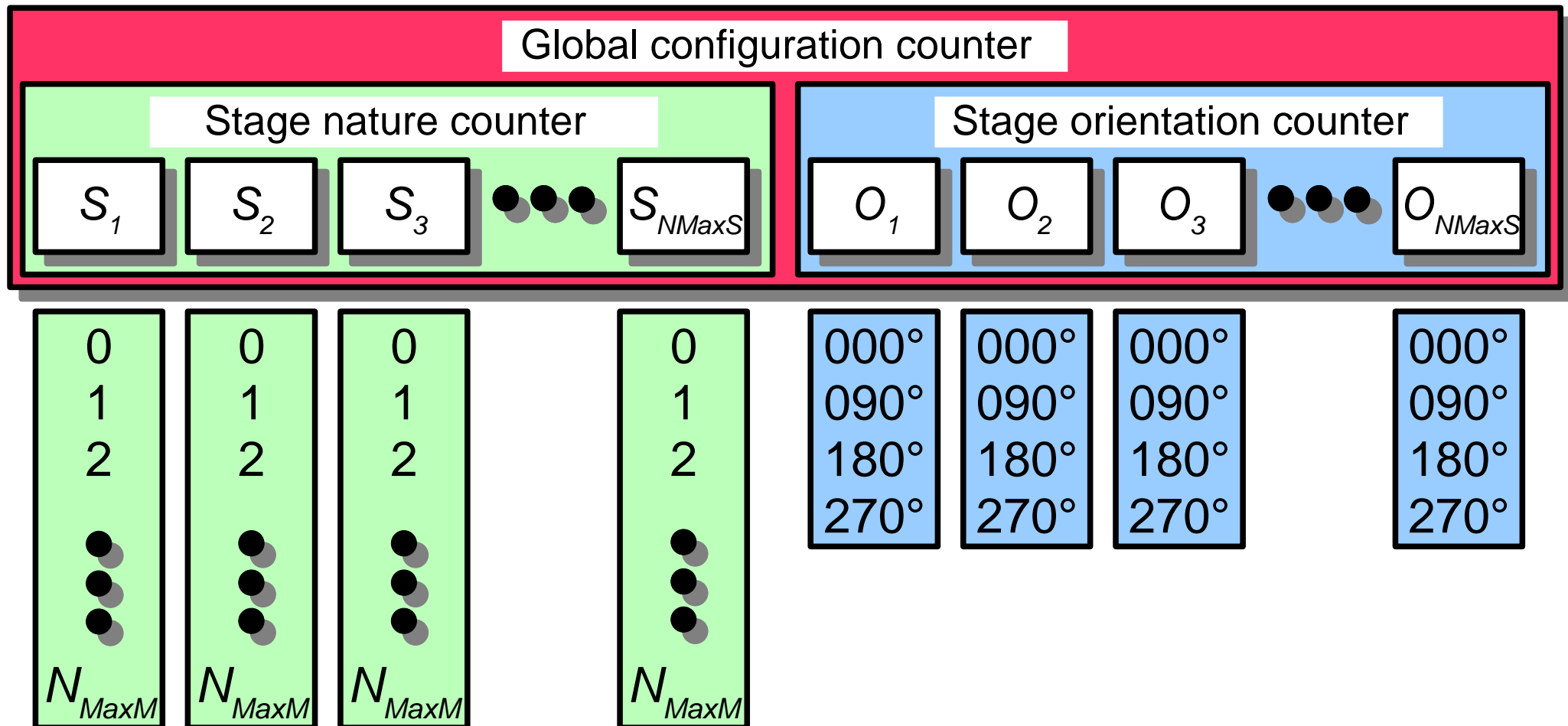
Worm gear sets

- Great ratios but efficiency sometimes small
- Two shaft settings
- Ratios 8, 16 or 32
- 4 threads / 32 teeth, ratio 8, efficiency 85%
- 1 thread / 16 teeth, ratio 16, efficiency 75%
- 1 thread / 32 teeth, ratio 32, efficiency 67%
- Number of threads $\uparrow \Rightarrow$ ratio \downarrow but efficiency \uparrow
- Number of teeth $\uparrow \Rightarrow$ ratio \uparrow , dimensions \uparrow but efficiency \downarrow



Exploration

- Combinatorial exploration
- Global **hybrid** configuration counter :
 - Stage nature (base N_{MaxM})
 - Stage orientation (base 4)



Elimination Rules

- The domain of configurations increases greatly
- Elimination rules can be refined
 - ➔ Limitation of the number of stages with orthogonal shafts

➔ Good efficiency

$$\eta_C \geq \eta_S$$

with $\eta_C = \prod_{i=1}^{N_{MaxS}} \eta_i$

➔ Good speed ratio

$$U_S - \Delta_U \leq U_C \leq U_S + \Delta_U$$

with $U_C = \prod_{i=1}^{N_{MaxS}} U_i$

➔ Good rotation sense

➔ Good absolute orientation of output shafts

$$\vec{Z}_{OC} = \vec{Z}_{OS} \quad \text{with} \quad \vec{Z}_{OC} = \prod_{i=1}^{N_{MaxS}} \mathbb{R}_i \vec{Z}_{IC}$$

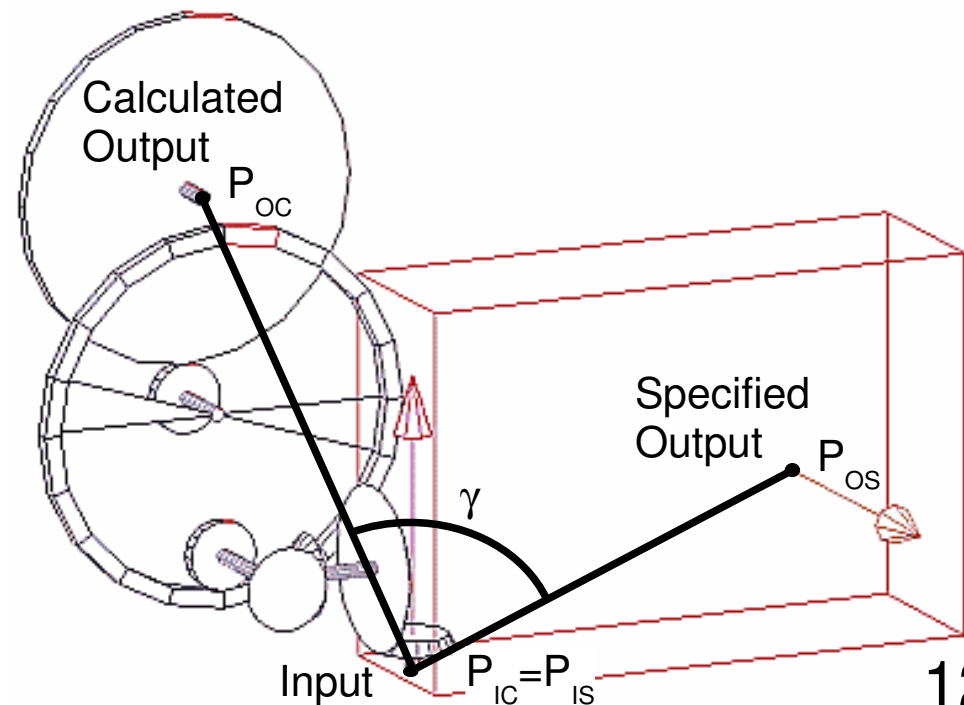
C = Calculated
S = Specified

➔ Correct relative I/O locations

$$\gamma = (\overrightarrow{P_{IC} P_{OC}}, \overrightarrow{P_{IS} P_{OS}}) < 90^\circ$$

with $P_{OC} = \prod_{i=1}^{N_{MaxS}} \mathbb{C}_i P_{IC}$

- Qualitative and non dimensional



Sorting Criteria (1/21/2)

- Best configurations should be sorted first
- Five performance functions

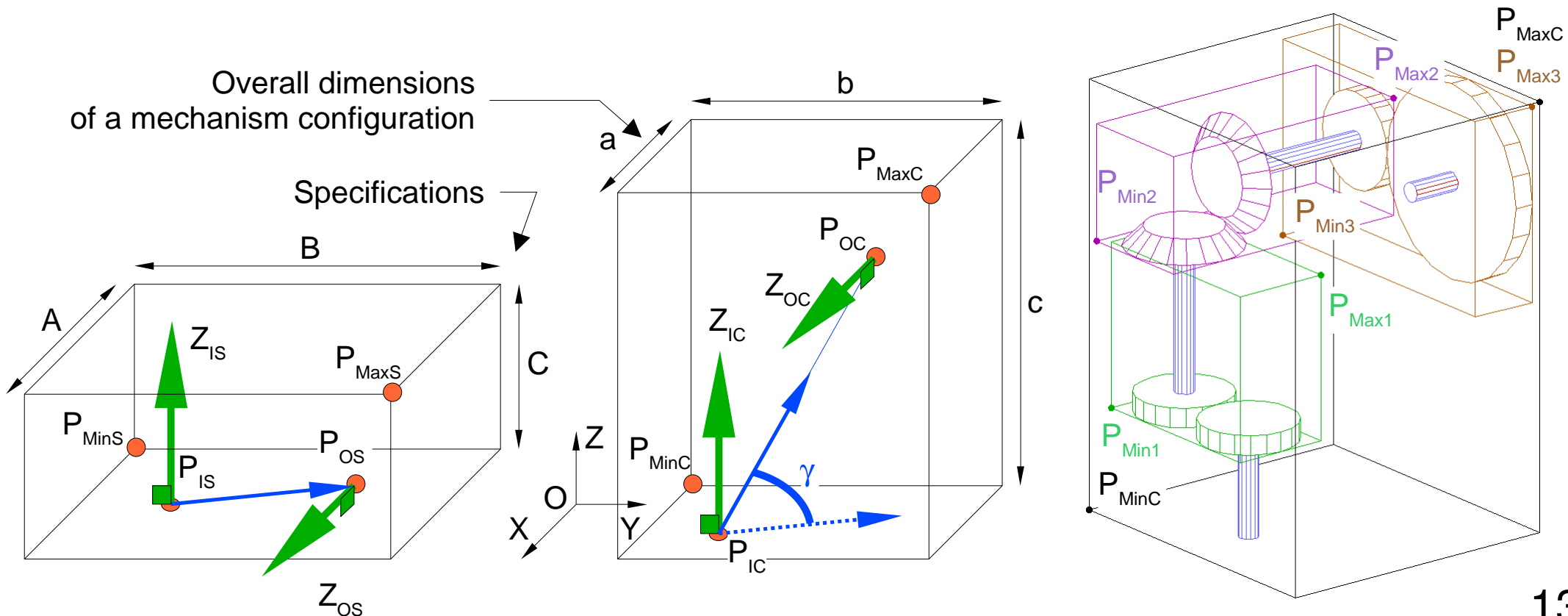
➔ Mechanism nature quality

- Power transmission ability
- Fabrication cost
- Mounting cost

➔ Overall proportion quality

- From 0 (perfect fitting)
- To infinity (infinite extension along one axis)

$$F_P = \left| \frac{a}{A} - \frac{b}{B} \right| + \left| \frac{b}{B} - \frac{c}{C} \right|$$



Sorting Criteria (1/22/2)

- Five performance functions

➔ Input location quality

$$F_I = (|NX_{IC} - NX_{IS}| + |NY_{IC} - NY_{IS}| + |NZ_{IC} - NZ_{IS}|) / 3$$

with
$$NX_{IC} = \frac{X_{IC} - X_{MinC}}{X_{MaxC} - X_{MinC}} \quad \text{and} \quad NX_{IS} = \frac{X_{IS} - X_{MinS}}{X_{MaxS} - X_{MinS}}$$

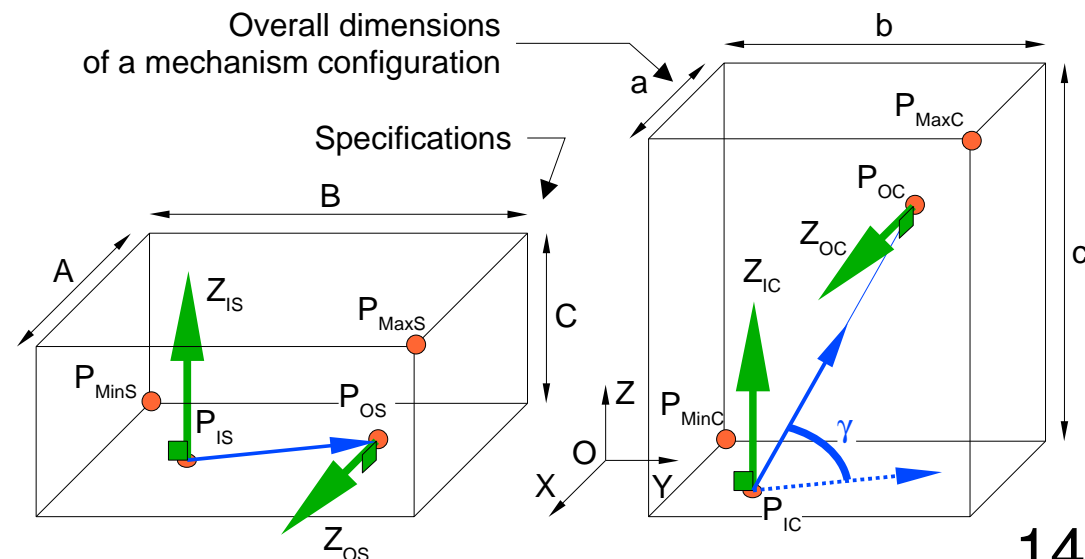
- NX_{IC} represent the non dimensional position in % of P_{IC} along the specification box
- $F_I = 0$ for an input perfectly fitting specifications
- $F_I = 1$ for an input diagonally opposed to requirements

➔ Output location quality

➔ Relative I/O location quality

$$F_{IO} = 1 - \cos(\gamma)$$

- $F_{IO} = 0$ when relative I/O location perfectly fit specifications
- $F_I = 1$ when I/O is very far from expected



Example

Design of the following mechanism :

- Orthogonal I/O shafts
- Efficiency > 90%
- Speed ratio around 47
- Reversing sense
- No more than 4 stages

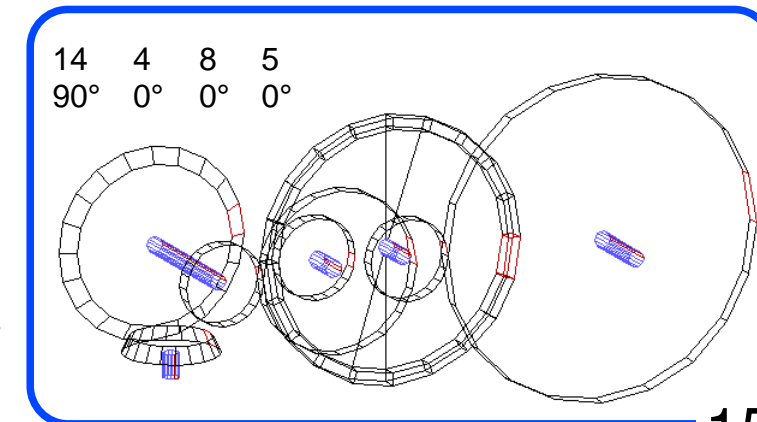
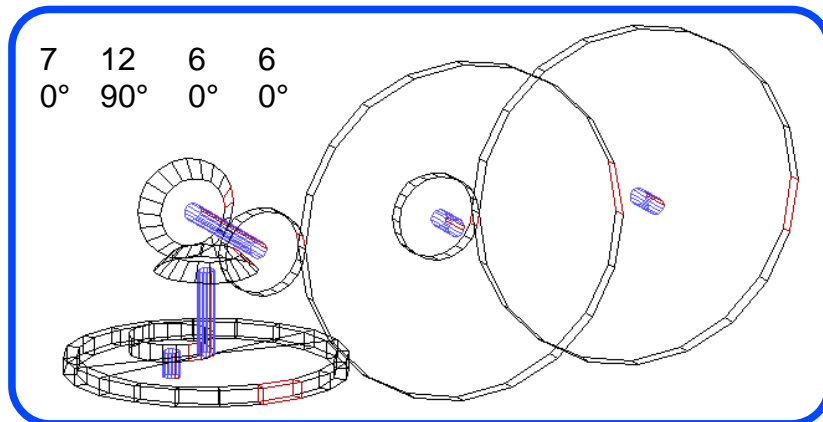
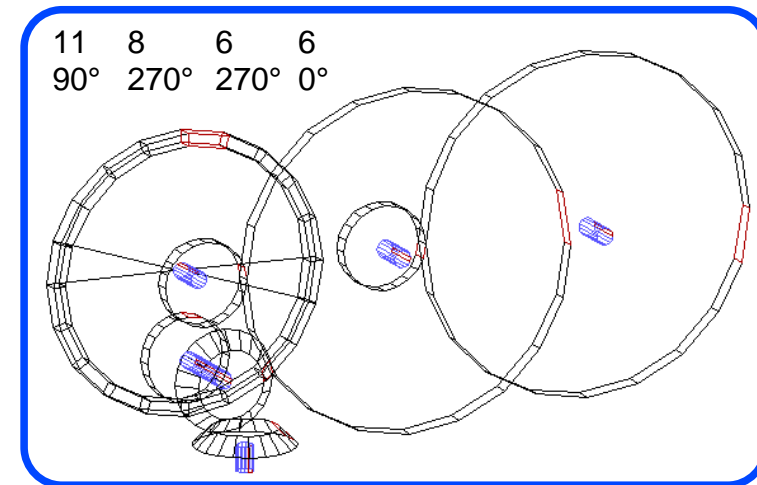
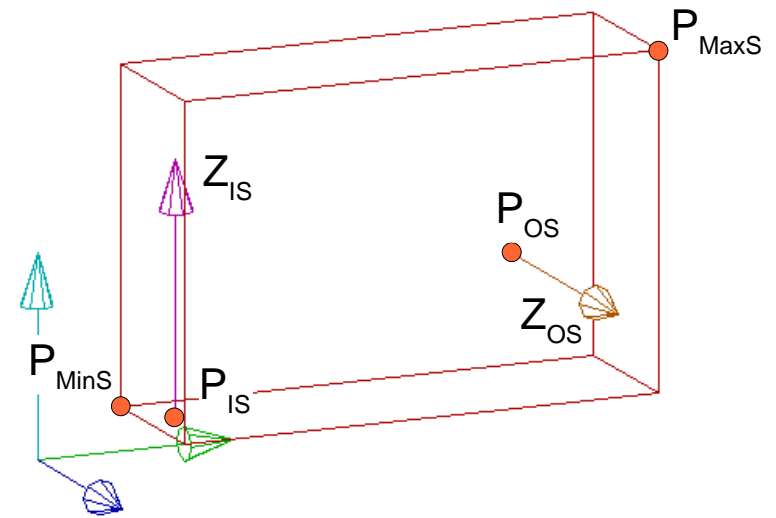
Results :

- 10 240 000 combinations
- Less than 5 seconds on a PIII 650 Mhz
- No solutions with $\Delta U = 0$
- 5723 solutions with $\Delta U = 1$ (space reduced by a factor 2000)
- Most of time spent in Exploration and Elimination phases
- High efficiency of **qsort** method (average running time $N \cdot \log(N)$)

Example : 10^6 combinations sorted in 10 seconds

- Time may be cut down by changing elimination rule order

Example : Orientation rule from first to last place
Computing time from 45 to 4 seconds



Conclusion

- A new method for designing transmission mechanisms with **standard components** and **standard orientations**
- Advantages
 - Standard components : more precise and **realistic** particularly for transmission ratio and efficiency
 - Solutions are **better defined** with more qualitative information
 - Realistic diameters and part orientations
 - **Compact** mechanisms are exhibited
 - Divides by **several thousands** the initial combination space
- To be Improved
 - Elimination rules may be refined
 - Sorting criteria may be refined
 - Faster computations with large databases
- An efficient tool for **suggesting ideas** to designer with exhaustivity

